

partial identification in linear models

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a multivariate normal i.i.d. error ε and a dependent n dimensional random variable $Y^* = (Y_1^*, \dots, Y_n^*)$, that is only known to lie in the interval $[\underline{Y}, \bar{Y}]$ of the known random variables \underline{Y} and \bar{Y} .

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which stands for a possible sample of Y compatible with the interval-valued observed data.

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to get an estimate $\hat{\beta}(y)$ for all y .

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The calculation of $\hat{\beta}(y)$ for all $y \in [\underline{y}, \bar{y}]$ is nothing else than the computation of the linear image of the 2 dimensional minkowski mean of the n line segments p_i formed by the points $(\underline{y}_i, x_i \cdot \underline{y}_i)$ and $(\bar{y}_i, x_i \cdot \bar{y}_i)$ under the mapping induced by the matrix P :

$$\hat{S} = P \cdot \left(\frac{1}{n} \bigoplus_{i=1}^n p_i \right)$$

Definition

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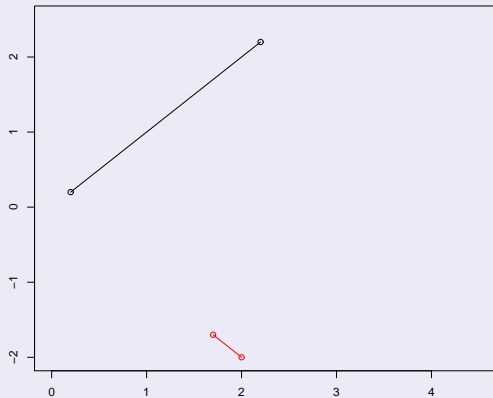
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The Minkowski Mean of n pointsets A_1, \dots, A_n is defined as:

$$\frac{1}{n} \bigoplus_{i=1}^n A_i := \left\{ \frac{1}{n} \sum_{i=1}^n a_i \mid a_i \in A_i, i = 1, \dots, n \right\}$$

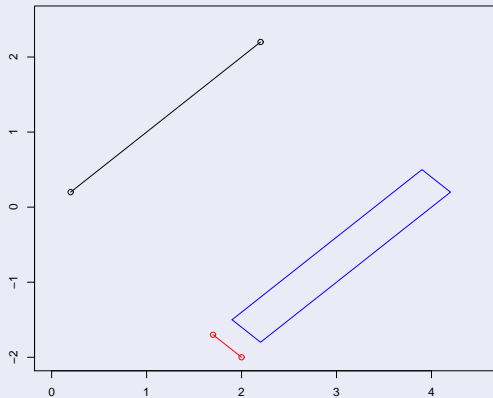
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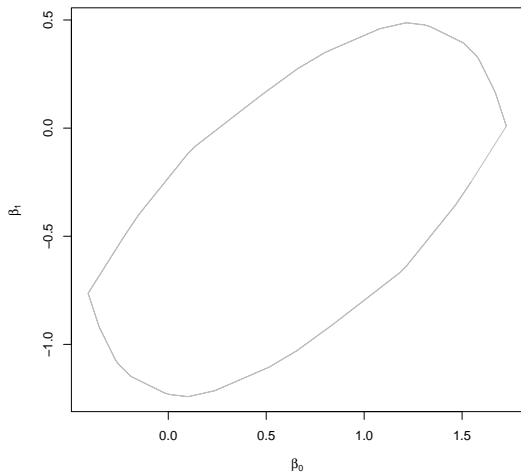
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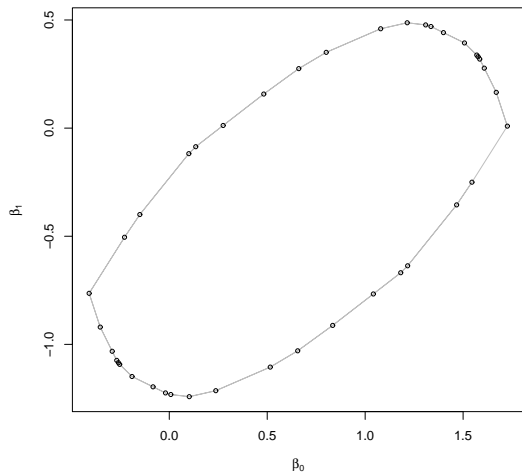
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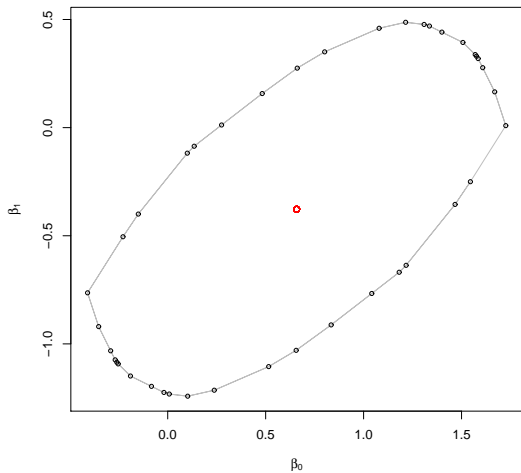
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- a) it has finite many extremepoints.



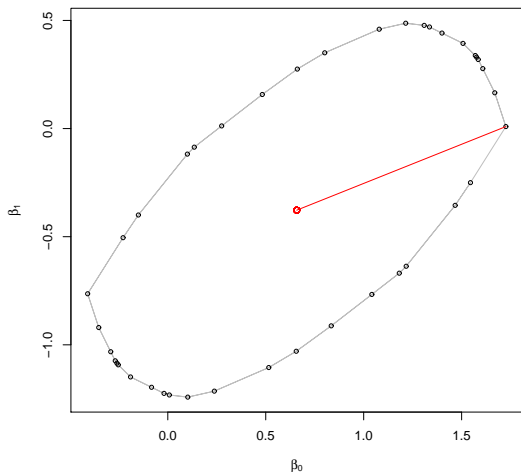
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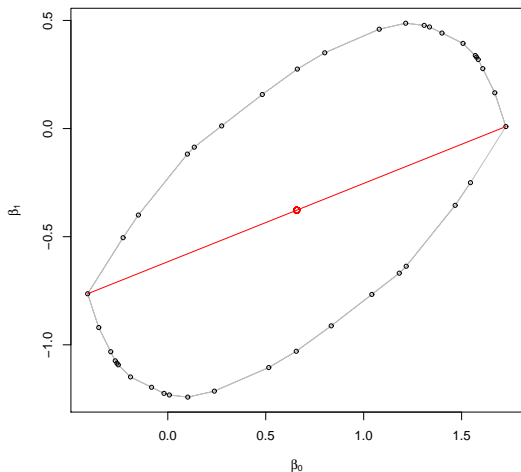
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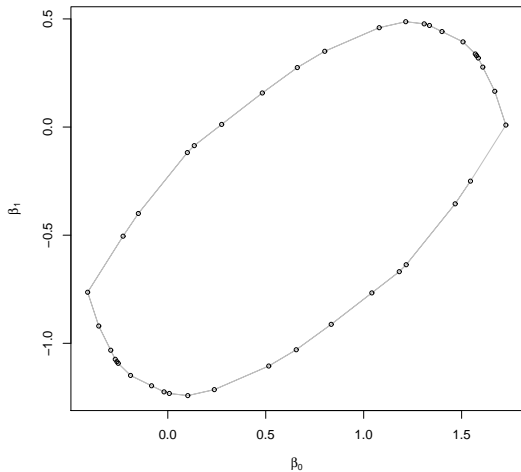
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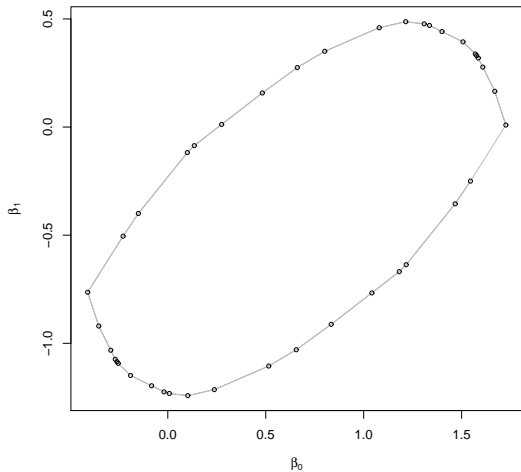
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c) in geometry it is, as the Minkowski Sum of n line segments, called a zonotope.



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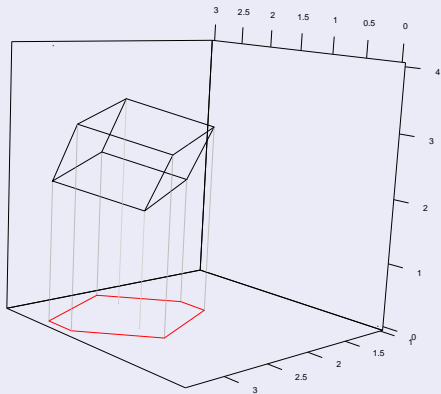
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$$\hat{S} = \text{co} \{ A \cdot y \mid y \text{ is a pseudodata} \}$$

We have two perspectives on \hat{S}

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$$\left\{ \left(\begin{array}{c} \mathbb{E}(Y) \\ \mathbb{E}(X \cdot Y) \end{array} \right) \middle| y \in [\underline{y}, \bar{y}] \right\} \text{ under } P.$$

So \hat{S} could at first hand be seen as a (set-valued) pointestimator for a (set-valued) parameter (the Aumann Expectation). Here we can use random set theory to analyze the estimator.

- (2) \hat{S} as the collection of all precise pointestimators obtained by all possible data-completions $y \in [\underline{y}, \bar{y}]$.

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and a metric d in \mathbb{R}^d (e.g. the euclidean metric).

This approach is developed in Beresteanu, Molinari 2008:

There the authors estimate \hat{S} and draw bootstrap-samples from the data to estimate further \hat{S}^* and look on the distribution of $H(\hat{S}, \hat{S}^*)$. From this distribution they obtain critical value c_α and construct the confidence collection

$$HCR = \bigcup_{\substack{S \in \mathbb{R}^d \\ dH(S, \hat{S}) \leq c_\alpha}} S.$$

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If one is in the situation, that there is a precise parameter β behind the scenes, it would be sufficient, that a confidence region covers not necessarily the whole sharp identification region but only the true parameter β with at least probability α , which is a weaker demand. So in this situation HCR is a (conservative) confidence region for the true parameter β .

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$$CE(y) := \left\{ \beta \mid (\beta - \hat{\beta}(y))' (X'X) (\beta - \hat{\beta}(y)) \leq (p+1) \cdot \hat{\sigma}^2(y) \cdot F_{1-\alpha}(p+1, n-p+1) \right\}.$$

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Under some not too strong conditions the simple confidence region SCR is a subset of the ellipsoid-type-confidence region

$$ECR := \text{co} \left(\bigcup_{c \in \{x_1, \dots, x_n\}} CE(y_{\geq c}^u) \cup CE(y_{\geq c}^l) \right)$$

Definition

Let the functions f , g and esd be defined as:

$$f : \hat{S} \rightarrow [\underline{y}, \bar{y}] : \beta \mapsto Q^{-1}(\beta) = \{y \in [\underline{y}, \bar{y}] \mid Qy = \beta\}$$

$$g : \hat{S} \rightarrow \mathbb{R} : \beta \mapsto \sup_{y \in f(\beta)} esd(y)$$

$$\begin{aligned} esd : [\underline{y}, \bar{y}] \rightarrow \mathbb{R} : y \mapsto esd(y) &:= sd(y - X\hat{\beta}(y)) \\ &= sd(\varepsilon) \\ &= \frac{n}{n-p-1} \sqrt{\frac{1}{n} \sum_{i=1}^n \varepsilon_i^2 - \left(\frac{1}{n} \sum_{i=1}^n \varepsilon_i \right)^2}. \end{aligned}$$

Lemma

Let a partially identified linear model $y = \beta_0 + \beta_1 \cdot x$ with x_i, y_i and \bar{y}_i i.i.d with existing expectations and variances and a nondegenerate sharp identification region S (meaning S has nonempty interior) be given.

If the function g is greater than a positive constant c (independent from n) with probability 1 for all $\hat{\beta}$ of the boundary $\partial \hat{S}$ of the Sir-estimator \hat{S} , then the simple confidence region is a subset of the ellipsoid-type-confidence region

$$ECR := \text{co} \left(\bigcup_{c \in \{x_1, \dots, x_n\}} CE(y_{\geq c}^u) \cup CE(y_{\geq c}^l) \right)$$

with arbitrary high probability $p < 1$, if $n = n(p)$ is large enough.

short simulationstudy:

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for 4 coarsening-processes:

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- coarsening 3: $\underline{y} = y - \varepsilon^2 \cdot 10^{-5}$, $\bar{y} = y + \varepsilon_2^2 \cdot 10^{-5} \cdot p$, $p \sim B(n, 0.05)$

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- coarsening 3: $\underline{y} = y - \varepsilon^2 \cdot 10^{-5}$, $\bar{y} = y + \varepsilon_2^2 \cdot 10^{-5} \cdot p$, $p \sim B(n, 0.05)$
- coarsening 4: $\underline{y} = y$

coarsening	N	SIR	HCR	ECR
1	10	0.96	1	1
1	100	1	1	1
1	1000	1	1	1
2	10	0.43	1	0.99
2	100	0.59	0.99	0.99
2	1000	0.80	1	1
3	10	0		1
3	100	0	0.92	0.95
3	1000	0	0.7?	
4	10	0.22	1	1
4	100	0.54		1
4	1000	0.82	1	1

coarsening	N	SIR	HCR	ECR
1	10	7.18	102.33	55.40
1	100	6.22	14.31	13.07
1	1000	6.14		8.08
2	10	5.33	25.81	22.90
2	100	5.60	8.79	8.67
2	1000	5.62	6.57	6.51
3	10	$7 \cdot 10^{-11}$		3.37
3	100	$6.29 \cdot 10^{-11}$	0.19	0.19
3	1000	$6.39 \cdot 10^{-11}$	0.02	0.02
4	10	9.90	15848.89	10485.69
4	100	1.22		87.30
4	1000	0.31	1.48	1.57

One „real-world-example“:

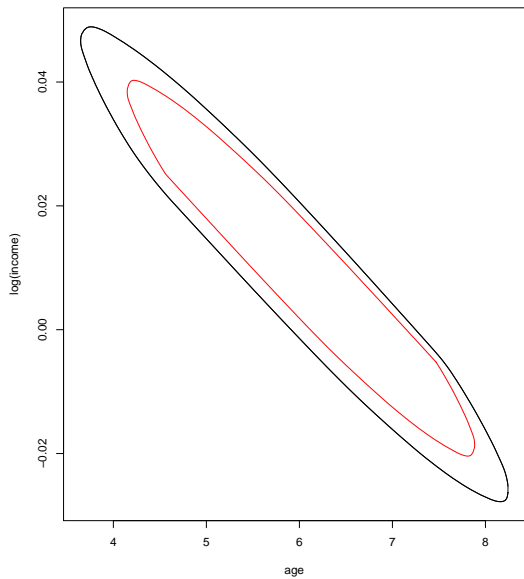
One „real-world-example“: Allbus data:





One „real-world-example“: Allbus data:

- sample from East Germany ($n = 1077$)

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- sample from East Germany ($n = 1077$)
- age (x , precise) and logarithm of income (y , interval-valued)



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