

# A note on sharp identification regions

## Definition

Let  $P := \{\mathbb{P}_\theta \mid \theta \in \Theta\}$  be a statistical model and

- $Y, \dots$  unobservable random variables,
- $X, \underline{Y}, \bar{Y}, \dots$  observable random variables w.r.t an underlying probability space  $(\Omega, \mathcal{F}, \mathbb{P})$ .
- The joint distribution of the random Variables  $X, Y, \underline{Y}, \bar{Y}$  under a model  $P_\theta$  is denoted with  $F_\theta$  and the joint distribution under the „true model“  $\mathbb{P}$  is denoted with  $F^{X, Y, \underline{Y}, \bar{Y}}$ .
- The unobserved variables fulfill a certain condition  $C(X, Y, \underline{Y}, \bar{Y}) = 1$ .  
e.g.  $\underline{Y} \leq Y \leq \bar{Y}$  or  $\forall X : \mathbb{E}(\underline{Y} \mid X) \leq \mathbb{E}(Y \mid X) \leq \mathbb{E}(\bar{Y} \mid X)$ .

## Definition

- Two parameters  $\theta_1$  and  $\theta_2$  are undistinguishable (i.e.  $\theta_1 \sim \theta_2$ ) if the corresponding models  $\mathbb{P}_{\theta_1}$  and  $\mathbb{P}_{\theta_2}$  are empirically undistinguishable, which means, that the distributions of the observable variables are the same:

$$F_{\theta_1}^{X, Y, \bar{Y}} = F_{\theta_2}^{X, Y, \bar{Y}}.$$

## Definition

A statistical model  $P$  is called *point-identified*, if any two different parameters  $\theta_1$  and  $\theta_2$  are empirically distinguishable, i.e.:

$$\sim = \Delta_{\Theta} = \{(\theta, \theta) \mid \theta \in \Theta\}.$$

Otherwise it is called *partially identified*.

## Example

The simple linear model

$$\Theta = B \times \mathbb{R}_{\geq 0} \times \mathcal{Z}(\mathbb{R}_{\geq 0}) \times \mathcal{Z}(\mathbb{R}_{\geq 0})$$

with  $B = \mathbb{R}^2$ . For  $\theta = (\beta, \sigma^2, \sigma_l, \sigma_u) \in \Theta$ , the random variables are defined as:

$$Y = X\beta + \varepsilon$$

$$\underline{Y} = X\beta + \varepsilon - \sigma_l$$

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with  $\varepsilon \sim N(0, \sigma^2 I)$ .

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Here we are only interested in the values of  $\beta \in B$ .

*This model is only partially identified. For example*

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*Moreover, the quotient space  $\Theta_{/\sim}$  is not of the form*

$$\Theta_{/\sim} = B_{/\approx} \times \text{„rest“},$$

*so we must factorize the whole space  $\Theta$  and not only the interesting  $B$  to make the model point-identified.*



*Estimation*



*Model*



*Pediction*

*Estimation*



*Model*



*Prediction*

*„model as a truth to be estimated“*

*„model as a tool to be applied“*

*Estimation*



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e.g.:

*least squares estimator*



*linear model*



*best linear predictor*

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$$\begin{aligned} & Y \sim F_\theta \\ \iff & F^Y = F_\theta^Y \\ \iff & L(F_\theta^Y, F) = 0 \end{aligned}$$

for some distance-function  $L(\cdot, \cdot)$ .

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The actual problem is, that  $F^Y$  is unknown  $\implies$  later.

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## Now: Linear Model

We are only interested in the components  $(\beta_0, \beta_1)$  of an element  $\theta = ((\beta_0, \beta_1), \sigma^2, \sigma_l, \sigma_u) \in SER$  and denote the set

$$\{(\beta_0, \beta_1) \mid ((\beta_0, \beta_1), \sigma^2, \sigma_l, \sigma_u) \in SER\}$$

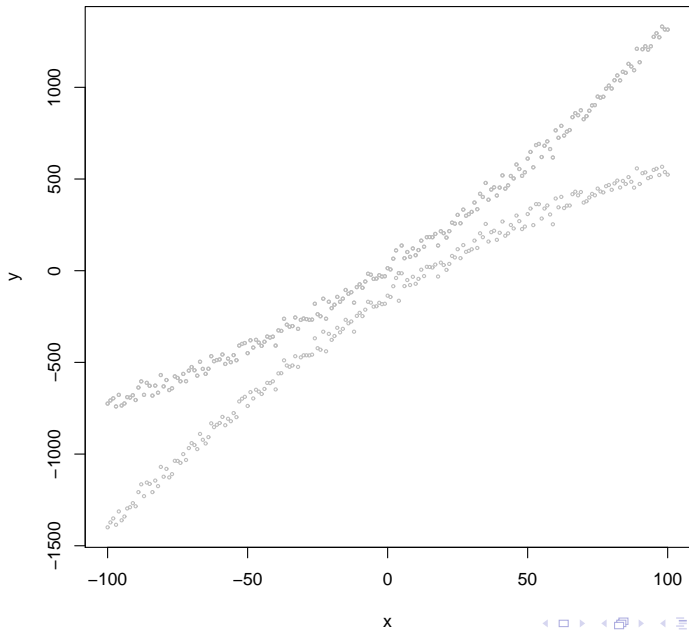
as the sharp estimation region (analogously for the sharp prediction region).

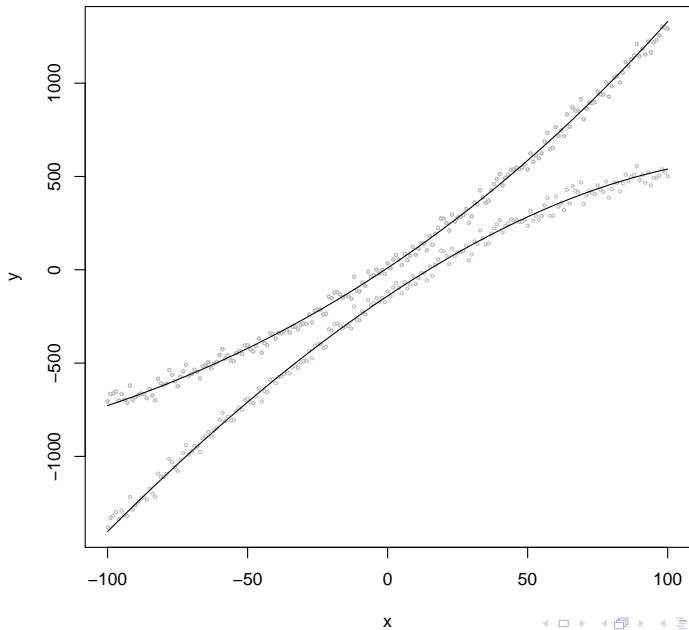
## Linear Model

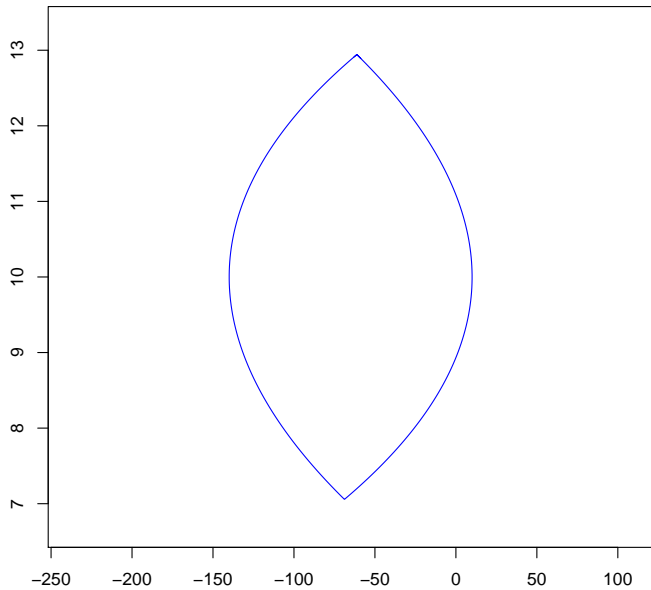
$$SER = \{\beta \in B \mid \mathbb{E}(\underline{Y} \mid X) \leq X\beta \leq \mathbb{E}(\bar{Y} \mid X)\}$$

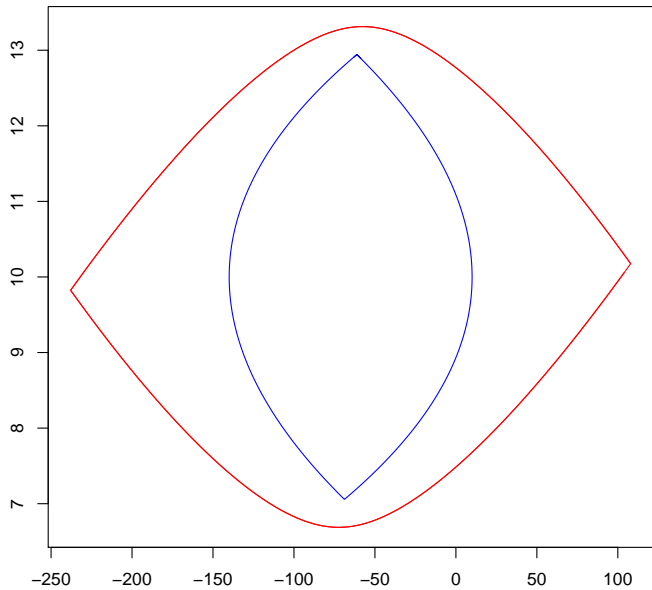
$$SPR = \{\operatorname{argmin}_{\beta \in B} \mathbb{E}((X\beta - Y)^2) \mid Y \in [\underline{Y}, \bar{Y}]\}$$

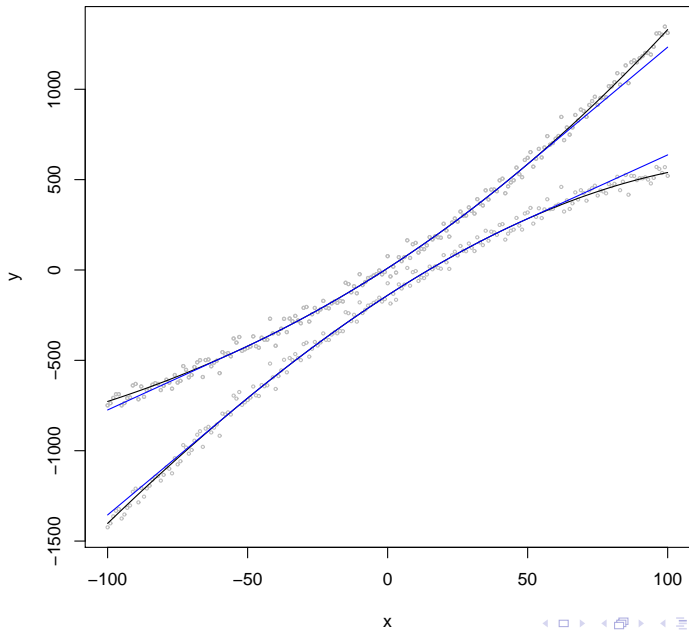
$$= \{(X'X)^{-1}X'Y \mid Y \in [\underline{Y}, \bar{Y}]\}$$



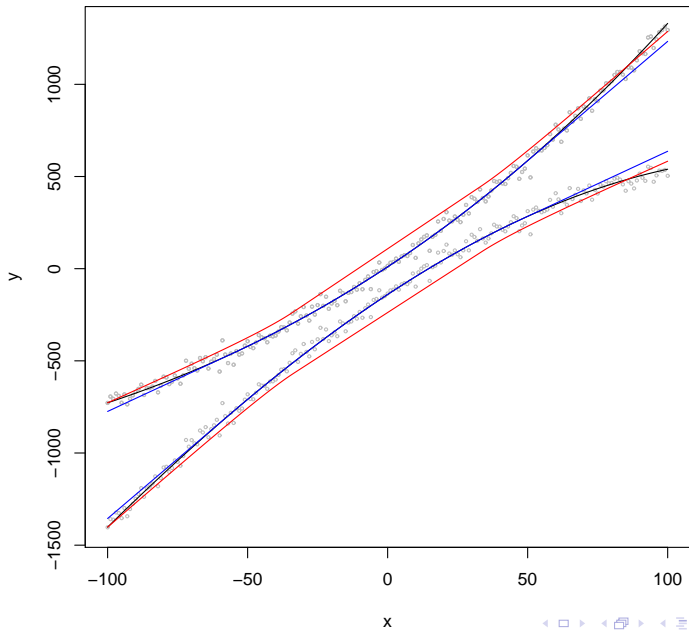












## Theorem

Let  $I \subset \mathbb{R}^2$  be a compact convex set. Then there exist random variables  $X, \underline{Y}, \bar{Y}$  such that

$$SER(X, \underline{Y}, \bar{Y}) = I,$$

namely:

$$X \sim N(0, 1)$$

$$\underline{Y} = \min\{\beta_0 + \beta_1 X \mid (\beta_0, \beta_1) \in I\}$$

$$\bar{Y} = \max\{\beta_0 + \beta_1 X \mid (\beta_0, \beta_1) \in I\}.$$

## Definition

### *The Minkowski-Sum*

$$M = \bigoplus_{i=1}^n l_i = \left\{ \sum_{i=1}^n p_i \mid p_i \in l_i \right\}$$

of  $n$  line-segments  $l_i \subseteq \mathbb{R}^d$  is called a **zonotope**.

A zonotope is a convex, compact and centrally symmetric polytope with finite many extremepoints and central-symmetric facets.

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## Definition

*A closed, centrally symmetric convex set  $Z \subseteq \mathbb{R}^d$  is called a **zonoid**, if it can be approximated arbitrarily closely by zonotopes (w.r.t. a metric, e.g. the Hausdorff distance).*

*For  $d = 2$  the zonoids are exactly the closed, centrally symmetric convex sets.*

## Lemma

Let  $I \subseteq \mathbb{R}^2$  be a zonoid in general position. Then there exists random variables  $X, \underline{Y}, \bar{Y}$  such that

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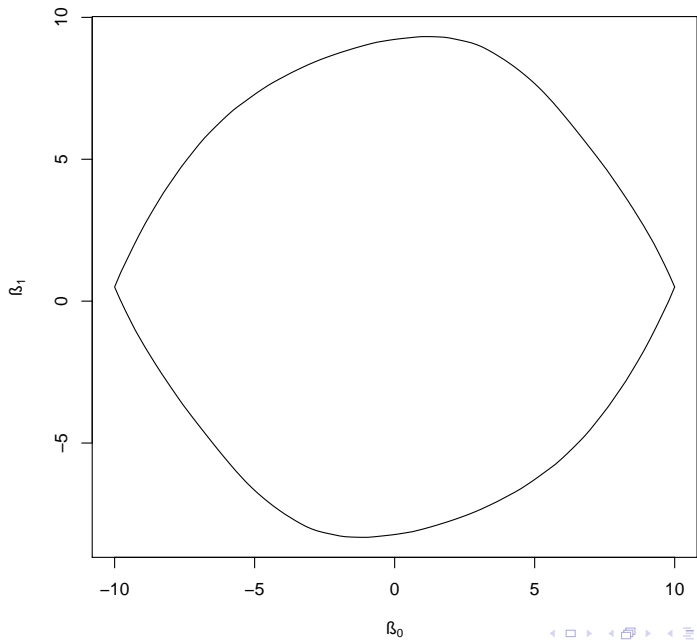
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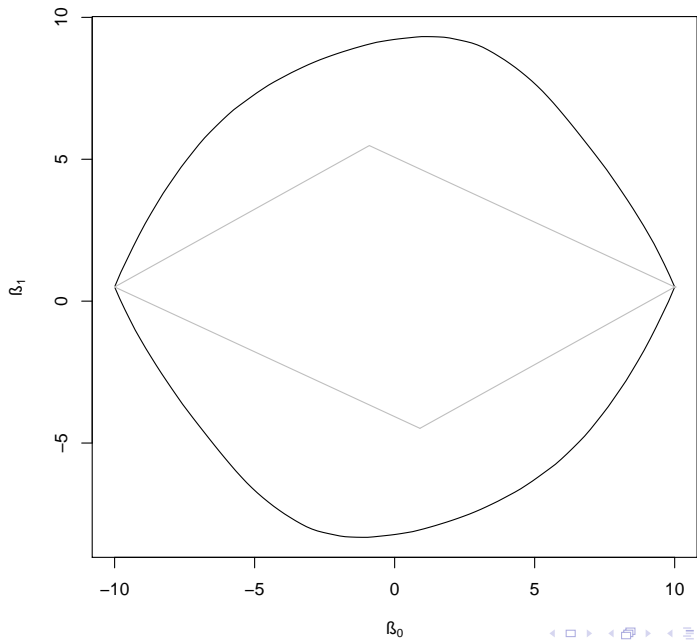
Let  $I = SPR(X, \underline{Y}^*, \bar{Y}^*) \subseteq \mathbb{R}^2$  be a zonoid and  $E \subseteq SER(X, \underline{Y}^*, \bar{Y}^*)$  an arbitrary compact convex set. Then for every  $\varepsilon > 0$  there exist random variables  $X, \underline{Y}, \bar{Y}$  such that:

$$d_H(SPR(X, \underline{Y}, \bar{Y}), I) \leq \varepsilon$$

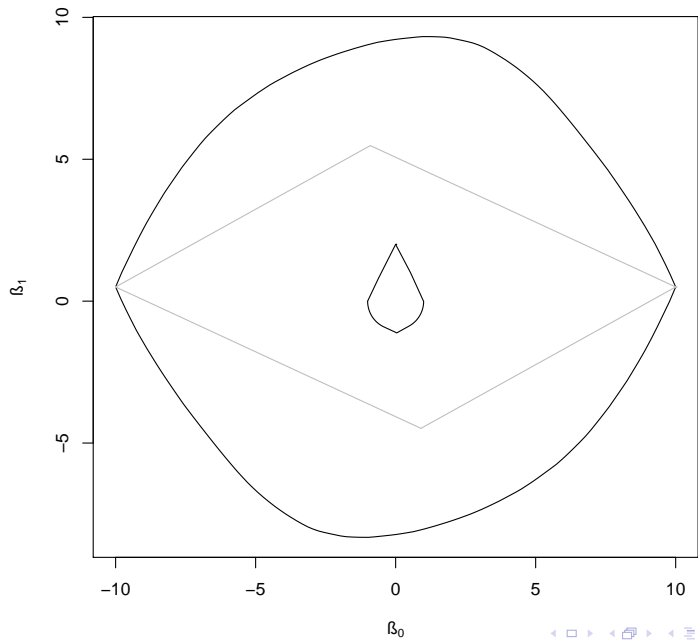
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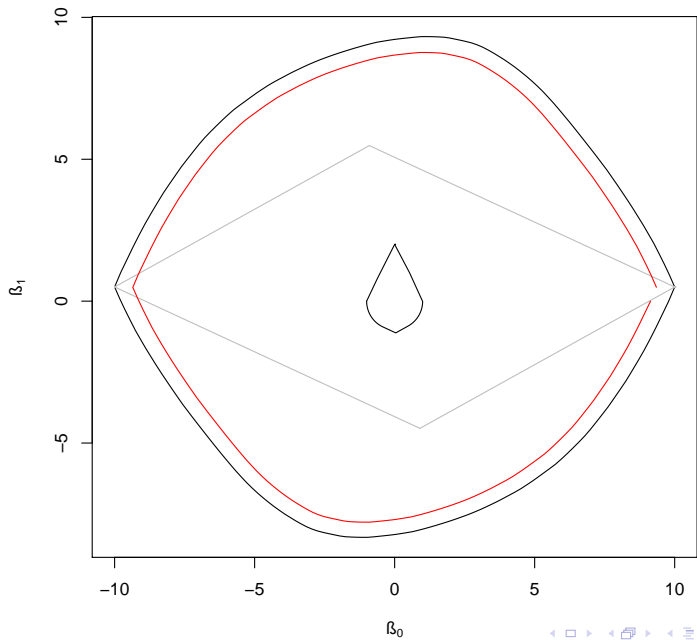
with the Hausdorff distance  $d_H$ .

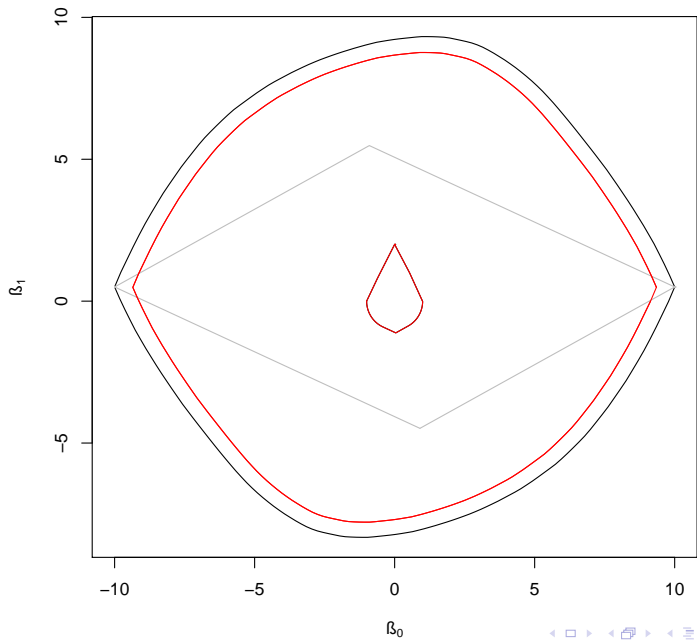












# Mappings between ordered sets

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## Definition

Let  $(P, \leq)$  and  $(Q, \sqsubseteq)$  be partially ordered sets. A pair  $(f, g)$  of mappings  $f : P \rightarrow Q$  and  $g : Q \rightarrow P$  is called **adjunction**, if:

$$\forall p \in P \forall q \in Q : p \leq g(q) \iff f(p) \sqsubseteq q.$$

In this case,  $f$  is called **left adjoint** and  $g$  is called **right adjoint**.

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- *Dempster-Shafer-Theory:*

*Multivalued mapping  $\Gamma : X \longrightarrow 2^S$  with corresponding*

$\tilde{\Gamma} : (2^X, \subseteq) \longrightarrow (2^S, \subseteq) : A \mapsto \bigcup_{a \in A} \Gamma(a)$  *and the operator*

$*$  :  $(2^S, \subseteq) \longrightarrow (2^X, \subseteq) : T \mapsto \{x \in X \mid \Gamma(x) \subseteq T\}$ .

*The pair  $(\tilde{\Gamma}, *)$  is an adjunction.*

*From this, the  $\infty$ -monotonicity of a Belief-function*

$$Bel = P \circ *$$

*with  $P$  a probability-measure follows immediately, since  $P$  is  $\infty$ -monotone and  $*$  is meet-preserving. Furthermore it is clear, that also  $Bel \circ *$  is  $\infty$ -monotone.*

# Examples of adjunctions

- *Lower coherent previsions:*

$$f : \underline{P} \mapsto \mathcal{M}(\underline{P}) = \{p \in \mathcal{P}(\Omega) \mid p \geq \underline{P}\} \text{ and}$$

$$g : M \mapsto \underline{P}_M : X \mapsto \inf_{p \in M} p(X) \text{ are an adjunction.}$$



# Examples of adjunctions

- *Formal concept analysis:*

*Incidence structure  $\mathbb{K} = (G, M, I)$*

*with  $G \dots$  objects,  $M \dots$  attributes and a relation  $I \subseteq G \times M$ .*

*$(g, m) \in I$  means object  $g$  has attribute  $m$  (also denoted as  $glm$ ).*

$$f : (2^M, \subseteq) \longrightarrow (2^G, \subseteq) : X \mapsto \{g \in G \mid \forall m \in X : glm\}$$

*„The set of all objects having all attributes in  $X$ “*

$$g : (2^G, \supseteq) \longrightarrow (2^M, \supseteq) : Y \mapsto \{m \in M \mid \forall g \in Y : glm\}$$

*„The set of all joint attributes of all objects in  $Y$ “.*

*The pair  $(f, g)$  is an adjunction.*

## Lemma

*Let  $(f, g)$  be an adjunction. Then the following holds:*

**A1**  *$g \circ f$  is extensive and  $f \circ g$  is intensive.*

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A6  $f$  is join-preserving and  $g$  is meet-preserving.

## Lemma

- *If  $P$  is a complete lattice, then  $f$  is a left adjoint, if and only if  $f$  is join-preserving.*
- *If  $Q$  is a complete lattice, then  $g$  is a right adjoint, if and only if  $g$  is meet-preserving.*



## Lemma

*The mapping*

$$SER : (\mathcal{Z}(\Omega), \leq) \longrightarrow (2^B, \subseteq) : (X, \underline{Y}, \bar{Y}) \mapsto \{\beta \mid \mathbb{E}(\underline{Y} | X) \leq \beta X \leq \mathbb{E}(\bar{Y} | X)\}$$

*with*

$$\boxed{(X_1, \underline{Y}_1, \bar{Y}_1) \leq (X_2, \underline{Y}_2, \bar{Y}_2)} \iff \boxed{\mathbb{E}(\underline{Y}_1 | X) \geq \mathbb{E}(\underline{Y}_2 | X) \ \& \ \mathbb{E}(\bar{Y}_1 | X) \leq \mathbb{E}(\bar{Y}_2 | X)}$$

*i.e.:  $(X_1, \underline{Y}_1, \bar{Y}_1)$  is more precise  
than  $(X_2, \underline{Y}_2, \bar{Y}_2)$*

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The corresponding left adjoint is the „prediction-operator“:

$$PR : (2^B, \subseteq) \longrightarrow (\mathcal{Z}(\Omega), \leq) : M \mapsto (X, \min_{\beta \in M} X\beta, \max_{\beta \in M} X\beta).$$

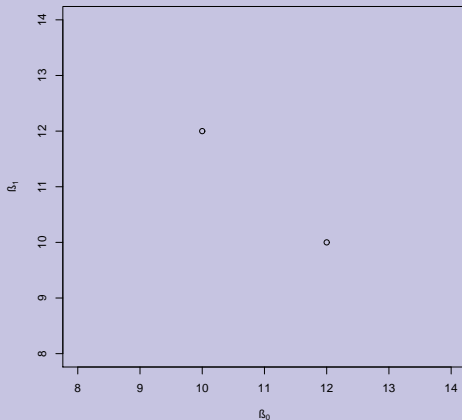
## Lemma

*Thus, the following holds:*

- A1  $SER \circ PR$  is extensive and  $PR \circ SER$  is intensive.*
- A2  $PR$  and  $SER$  are order-preserving.*
- A3  $PR \circ SER \circ PR = PR$  and  $SER \circ PR \circ SER = SER$  and thus  $PR \circ SER$  and  $SER \circ PR$  are idempotent.*
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- A5 The adjoints  $PR$  and  $SER$  are determining each other unambiguously.*
- A6  $PR$  is join-preserving and  $SER$  is meet-preserving.*

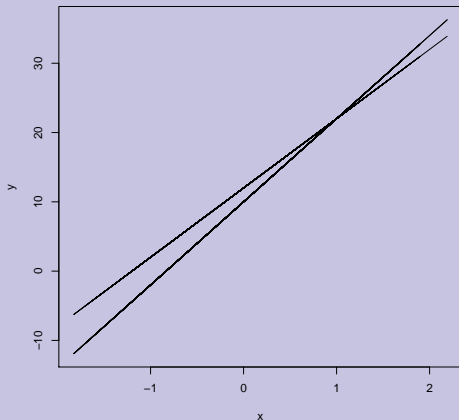
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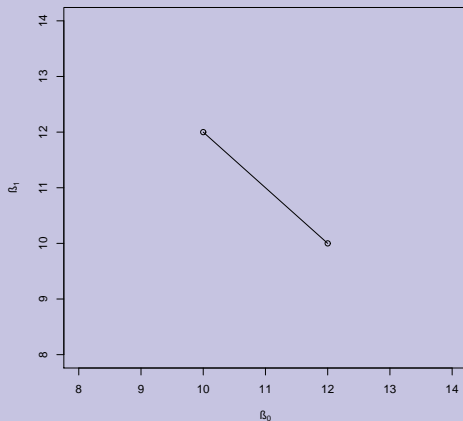
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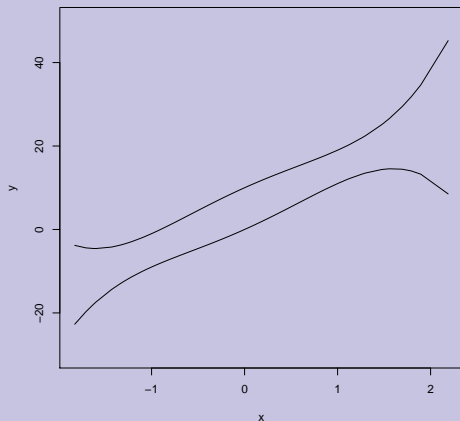
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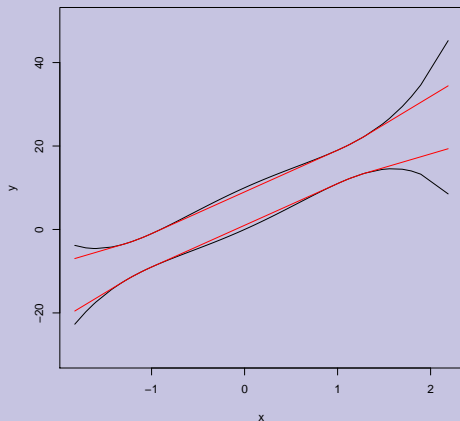
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*Thus, the following holds:*

- A1  $SER \circ PR$  is extensive and  $PR \circ SER$  is intensive.*
- A2  $PR$  and  $SER$  are order-preserving.*
- A3  $PR \circ SER \circ PR = PR$  and  $SER \circ PR \circ SER = SER$  and thus  $PR \circ SER$  and  $SER \circ PR$  are idempotent.*
- A4 From A1 - A3 it follows, that  $SER \circ PR$  is a hull operator and  $PR \circ SER$  is a kernel operator.*
- A5 The adjoints  $PR$  and  $SER$  are determining each other unambiguously.*
- A6  $PR$  is join-preserving and  $SER$  is meet-preserving.*

## Lemma

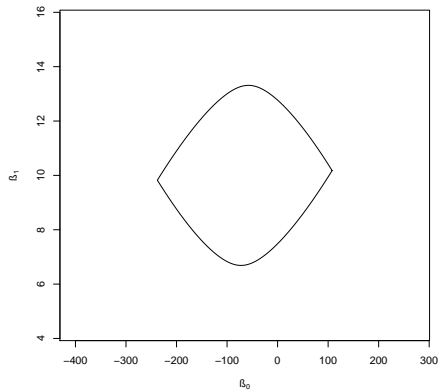
*The mapping*

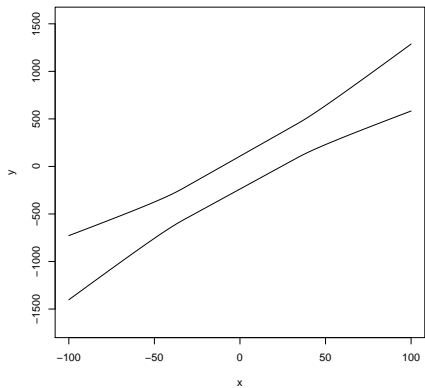
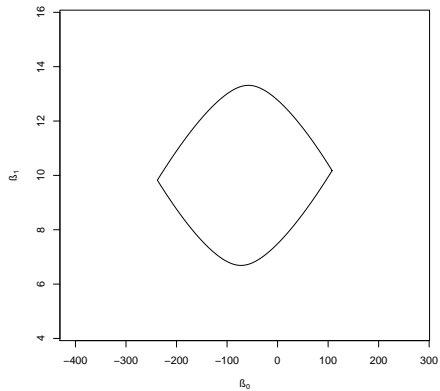
$$SPR : (\mathcal{Z}(\Omega), \leq) \longrightarrow (2^B, \subseteq) : (X, \underline{Y}, \bar{Y}) \mapsto \{(X'X)^{-1}X'Y \mid \underline{Y} \leq Y \leq \bar{Y}\}$$

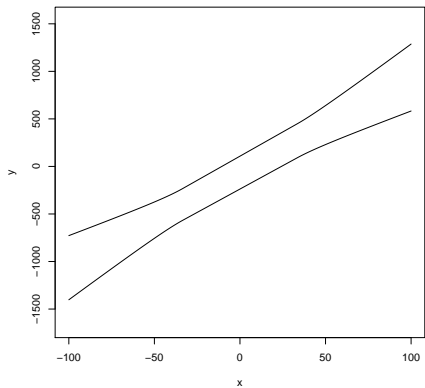
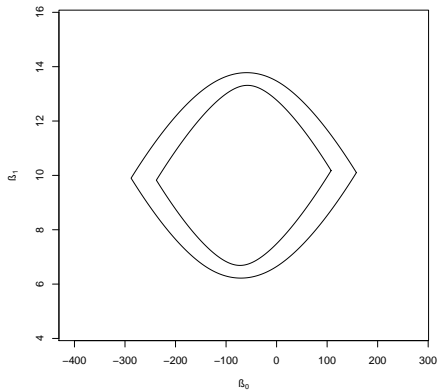
*is no right adjoint, since it is not meet-preserving.*

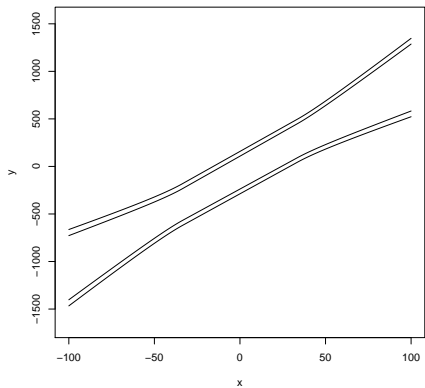
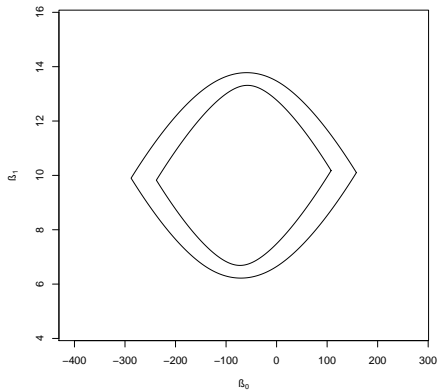
*In general  $SPR(Z_1 \wedge Z_2) \neq SPR(Z_1) \cap SPR(Z_2)$ , since the intersection of two zonoids is in general not a zonoid.*

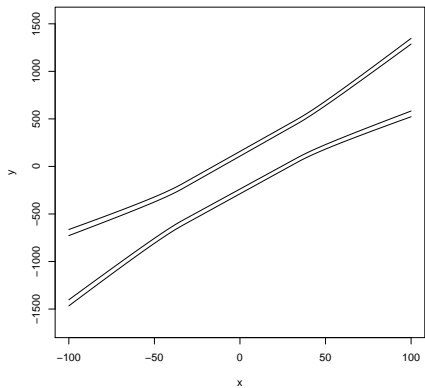
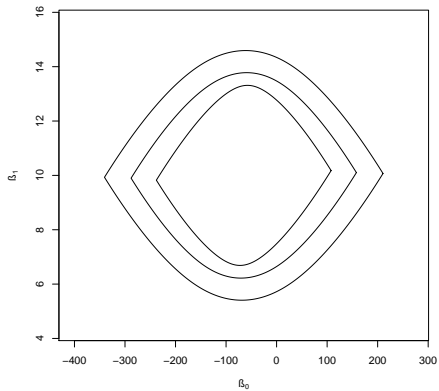
*Thus, in general, only  $SPR \circ PR \circ SPR \supseteq SPR$  holds.*

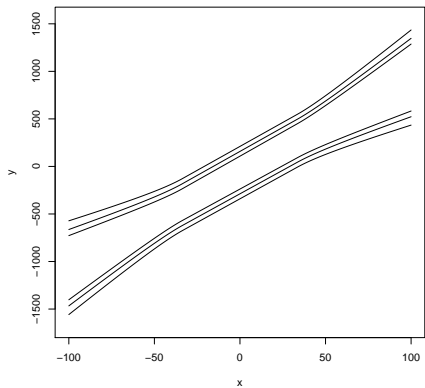
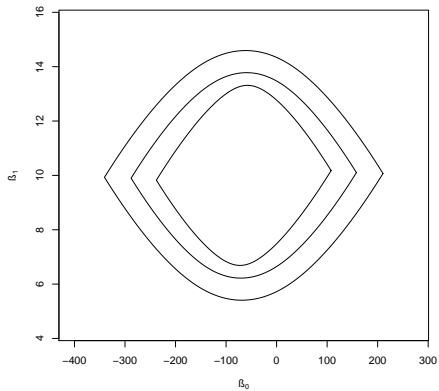




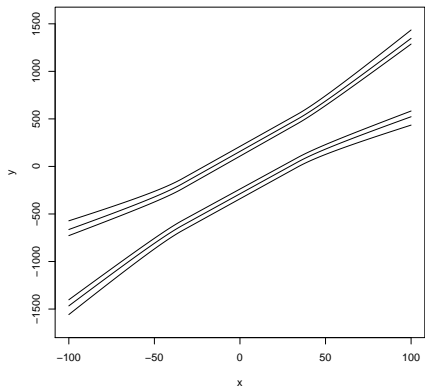
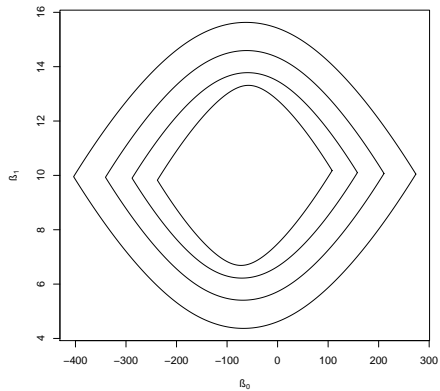


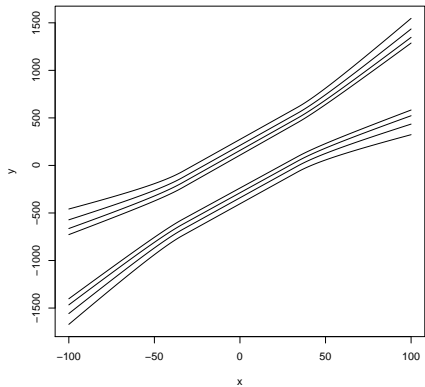
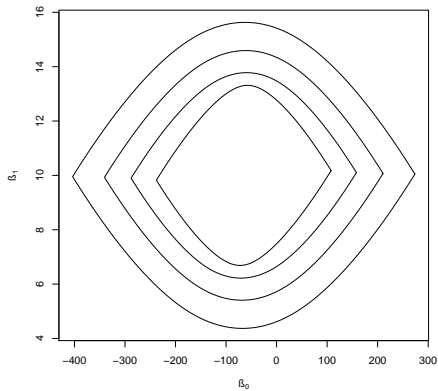












## Definition

Let  $E : (P, \leq) \longrightarrow (Q, \sqsubseteq)$  be a mapping.

The monotone hull of  $E$  is defined as:

$$H(E) : (P, \leq) \longrightarrow (Q, \sqsubseteq) : X \mapsto \bigvee_{Y \leq X} E(Y).$$

The monotone kernel of  $E$  is defined as:

$$K(E) : (P, \leq) \longrightarrow (Q, \sqsubseteq) : X \mapsto \bigwedge_{Y \geq X} E(Y).$$

These set-valued mappings are both order-preserving

(i.e.  $X \leq Y \implies (H(E))(X) \sqsubseteq (H(E))(Y)$  &  $(K(E))(X) \sqsubseteq (K(E))(Y)$ ).

# A criterion-function-based mapping

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## Lemma

Let the criterion-function  $Q : B \rightarrow \mathbb{R}$  be defined as:

$$Q(\beta) = \int \left\{ (\mathbb{E}(\underline{Y} | x) - x\beta)_+^2 + (\mathbb{E}(\bar{Y} | x) - x\beta)_-^2 \right\} d\mathbb{P}(x).$$

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Then the criterion-based mapping

$$E_Q : \mathcal{Z}(\Omega) \rightarrow 2^B : (X, \underline{Y}, \bar{Y}) \mapsto \underset{\beta \in B}{\operatorname{argmin}} Q(\beta)$$

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$$\text{SPR} = H(E_Q)$$

$$\text{SER} = K(E_Q).$$

# Estimation of SER and SPR



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*In general, there is no consistent and (in a certain sense) robust estimator of SER.*



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