Linear models and partial identification: Imprecise linear regression with interval data

We have to estimate the parameter  $\beta \in \mathbb{R}^{p+1}$ 

2

イロト イポト イヨト イヨト



We have to estimate the parameter  $\beta \in \mathbb{R}^{p+1}$  of a linear model

We have to estimate the parameter  $\beta \in \mathbb{R}^{p+1}$  of a linear model

$$Y^* = X\beta + \varepsilon$$

We have to estimate the parameter  $\beta \in \mathbb{R}^{p+1}$  of a linear model

$$Y^* = X\beta + \varepsilon$$

with a fixed design-matrix

$$X = \begin{pmatrix} 1 & X_{11} & X_{12} & \dots & X_{1p} \\ 1 & X_{21} & X_{22} & \dots & X_{2p} \\ & & & \vdots \\ 1 & X_{n1} & X_{n2} & \dots & X_{np} \end{pmatrix},$$

We have to estimate the parameter  $\beta \in \mathbb{R}^{p+1}$  of a linear model

$$Y^* = X\beta + \varepsilon$$

with a fixed design-matrix

$$X = \begin{pmatrix} 1 & X_{11} & X_{12} & \dots & X_{1p} \\ 1 & X_{21} & X_{22} & \dots & X_{2p} \\ & & & \vdots \\ 1 & X_{n1} & X_{n2} & \dots & X_{np} \end{pmatrix},$$

a multivariat normal i.i.d. error  $\varepsilon$ 

We have to estimate the parameter  $\beta \in \mathbb{R}^{p+1}$  of a linear model

$$Y^* = X\beta + \varepsilon$$

with a fixed design-matrix

$$X = \begin{pmatrix} 1 & X_{11} & X_{12} & \dots & X_{1p} \\ 1 & X_{21} & X_{22} & \dots & X_{2p} \\ & & & \vdots \\ 1 & X_{n1} & X_{n2} & \dots & X_{np} \end{pmatrix},$$

a multivariat normal i.i.d. error  $\varepsilon$  and a dependend *n* dimensional random variable  $Y^* = (Y_1^*, \dots, Y_n^*)$ ,

(ロ) (四) (E) (E) (E) (E)

We have to estimate the parameter  $\beta \in \mathbb{R}^{p+1}$  of a linear model

$$Y^* = X\beta + \varepsilon$$

with a fixed design-matrix

$$X = \begin{pmatrix} 1 & X_{11} & X_{12} & \dots & X_{1p} \\ 1 & X_{21} & X_{22} & \dots & X_{2p} \\ & & & \vdots \\ 1 & X_{n1} & X_{n2} & \dots & X_{np} \end{pmatrix},$$

a multivariat normal i.i.d. error  $\varepsilon$  and a dependend *n* dimensional random variable  $Y^* = (Y_1^*, \ldots, Y_n^*)$ , that is only known to lie in the intervall  $[\underline{Y}, \overline{Y}]$  of the known random variables  $\underline{Y}$  and  $\overline{Y}$ .

One simple approach:

2

・ロト ・四ト ・ヨト ・ヨト



One simple approach:

look at all possible candidates Y for the unknown  $Y^*$  compatible with the restriction  $Y\in[\underline{Y},\overline{Y}]$ 

One simple approach:

look at all possible candidates Y for the unknown  $Y^*$  compatible with the restriction  $Y \in [\underline{Y}, \overline{Y}]$  and estimate for all such candidates Y the corresponding estimates  $\hat{\beta}$  to get the set-valued estimator

・ロン ・四マ ・ヨン ・ヨン

One simple approach:

look at all possible candidates Y for the unknown  $Y^*$  compatible with the restriction  $Y \in [\underline{Y}, \overline{Y}]$  and estimate for all such candidates Y the corresponding estimates  $\hat{\beta}$  to get the set-valued estimator

$$\hat{\mathsf{S}}$$
 :=  $\{\hat{eta}(y)|y\in [\underline{y},\overline{y}]\}$ 

One simple approach:

look at all possible candidates Y for the unknown  $Y^*$  compatible with the restriction  $Y \in [\underline{Y}, \overline{Y}]$  and estimate for all such candidates Y the corresponding estimates  $\hat{\beta}$  to get the set-valued estimator

$$\hat{S}$$
 := { $\hat{eta}(y)|y\in [\underline{y},\overline{y}]$ }

where  $\underline{y}$  and  $\overline{y}$  are *n*-dimensional samples from  $\underline{Y}$  and  $\overline{Y}$  and *y* is a *n*-dimensional vector satisfying

$$y_i \in [\underline{Y}_i, \overline{Y}_i], i = 1, \ldots, n,$$

・ロト ・四ト ・ヨト ・ヨト - ヨ

One simple approach:

look at all possible candidates Y for the unknown  $Y^*$  compatible with the restriction  $Y \in [\underline{Y}, \overline{Y}]$  and estimate for all such candidates Y the corresponding estimates  $\hat{\beta}$  to get the set-valued estimator

$$\hat{S}$$
 := { $\hat{eta}(y)|y\in [\underline{y},\overline{y}]$ }

where  $\underline{y}$  and  $\overline{y}$  are *n*-dimensional samples from  $\underline{Y}$  and  $\overline{Y}$  and *y* is a *n*-dimensional vector satisfying

$$y_i \in [\underline{Y}_i, \overline{Y}_i], i = 1, \ldots, n,$$

which stands for a possible sample of Y compatible with the interval-valued observed data.

linear models and partial identification

Choose the classical linear estimator

2

Choose the classical linear estimator

$$\hat{\beta}(y) = (X'X)^{-1}X'y.$$

2

・ロト ・聞ト ・ヨト ・ヨト

Choose the classical linear estimator

$$\hat{\beta}(y) = (X'X)^{-1}X'y.$$

to get an estimate  $\hat{\beta}(y)$  for all y.

2

・ロト ・聞ト ・ヨト ・ヨト

$$\hat{\beta}(y) =$$

$$\hat{\beta}(y) = \begin{pmatrix} \beta_0 \\ \beta_1 \end{pmatrix}$$

$$\hat{\beta}(y) = \begin{pmatrix} \beta_0 \\ \beta_1 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & \bar{x} \\ \bar{x} & \bar{x}^2 \end{pmatrix}^{-1} \begin{pmatrix} \bar{y} \\ \overline{x \cdot y} \end{pmatrix}$$

イロト イロト イヨト イヨト 三日

()

β̂(

$$y) = \begin{pmatrix} \beta_0 \\ \beta_1 \end{pmatrix}$$
$$= \begin{pmatrix} 1 & \bar{x} \\ \bar{x} & \bar{x}^2 \end{pmatrix}^{-1} \begin{pmatrix} \bar{y} \\ \overline{x \cdot y} \end{pmatrix}$$
$$= \begin{pmatrix} 1 & \bar{x} \\ \bar{x} & \bar{x}^2 \end{pmatrix}^{-1} \begin{pmatrix} \frac{1}{n} \sum_{i=1}^n y_i \\ \frac{1}{n} \sum_{i=1}^n x_i \cdot y_i \end{pmatrix}$$

イロト イロト イヨト イヨト 二日

()

$$\hat{\beta}(y) = \binom{\beta_0}{\beta_1}$$

$$= \binom{1}{\bar{x}} \frac{\bar{x}}{x^2}^{-1} \binom{\bar{y}}{\bar{x} \cdot \bar{y}}$$

$$= \binom{1}{\bar{x}} \frac{\bar{x}}{x^2}^{-1} \binom{\frac{1}{n} \sum_{i=1}^n y_i}{\frac{1}{n} \sum_{i=1}^n x_i \cdot y_i}$$

$$=: P \cdot \binom{\frac{1}{n} \sum_{i=1}^n y_i}{\frac{1}{n} \sum_{i=1}^n x_i \cdot y_i}$$

2

イロト イヨト イヨト イヨト

()

#### Definition

The Minkowski Sum of two sets A, B in  $\mathbb{R}^d$  is defined as:

$$A \oplus B := \{a + b | a \in A, b \in B\}.$$

#### Definition

The Minkowski Sum of two sets A, B in  $\mathbb{R}^d$  is defined as:

$$A \oplus B := \{a + b | a \in A, b \in B\}.$$

The Minkowski Mean of n pointsets  $A_1, \ldots, A_n$  is defined as:

$$\frac{1}{n}\bigoplus_{i=1}^{n}A_{i}:=\left\{\frac{1}{n}\sum_{i=1}^{n}a_{i}\middle|a_{i}\in A_{i},i=1,\ldots,n\right\}$$

<ロト <回ト < 回ト < 回ト = 三日

#### Example

The Minkowski Sum of two line segments in  $\mathbb{R}^2$ :



2

イロト イロト イヨト イヨト

#### Example

The Minkowski Sum of two line segments in  $\mathbb{R}^2$ :



2

イロト イロト イヨト イヨト

The calculation of  $\hat{\beta}(y)$  for all  $y \in [\underline{y}, \overline{y}]$  is nothing else than the computation of the linear image of the 2 dimensional minkowski mean of the n line segments  $p_i$  formed by the points  $(\underline{y}_i, x_i \cdot \underline{y}_i)$  and  $(\overline{y}_i, x_i \cdot \overline{y}_i)$  under the mapping induced by the matrix P:

$$\hat{S} = P \cdot \left( \frac{1}{n} \bigoplus_{i=1}^{n} p_i \right)$$

・ロット (雪) ( 手) ( 日)

2

ヘロト ヘアト ヘビト ヘビト

a) it is

2

・ロト ・聞ト ・ヨト ・ヨト

a) it is (, as the linear image of a convex, bounded set)

э

・ロト ・四ト ・ヨト ・ヨト



a) it is (, as the linear image of a convex, bounded set) convex and bounded.

2

a) it is (, as the linear image of a convex, bounded set) convex and bounded.



2

a) it has finite many extremepoints.



・ロト ・ 日 ・ ・ ヨ ・ ・ ヨ ・

b) it is central symmetric with the center  $\hat{\beta}(\frac{y+\bar{y}}{2})$ .



・ロト ・四ト ・ヨト ・ヨト
c) it is central symmetric with the center  $\hat{\beta}(\frac{y+\overline{y}}{2})$ .



・ロト ・四ト ・ヨト ・ヨト

c) it is central symmetric with the center  $\hat{\beta}(\frac{y+\overline{y}}{2})$ .



・ロト ・四ト ・ヨト ・ヨト

c) its facets are central symmetric, too.



・ロト ・ 日 ・ ・ ヨ ・ ・ ヨ ・

c) in geometry it is, as the Minkowski Sum of n line segments, called a zonotope.



イロト イポト イヨト イヨト

2

$$\hat{S} = \{A \cdot y | y \in [\underline{y}, \overline{y}]\}$$

2

・ロト ・聞ト ・ヨト ・ヨト

$$\hat{S} = \{A \cdot y | y \in [\underline{y}, \overline{y}]\}$$

is the linear image of a *n*-dimensional cuboid

2

・ロト ・四ト ・ヨト ・ヨト

$$\hat{S} = \{A \cdot y | y \in [\underline{y}, \overline{y}]\}$$

is the linear image of a n-dimensional cuboid or equivalently the affine linear image of the n-dimensional unit-cube:

・ロト ・ 雪ト ・ ヨト ・ ヨト

$$\hat{S} = \{A \cdot y | y \in [\underline{y}, \overline{y}]\}$$

is the linear image of a n-dimensional cuboid or equivalently the affine linear image of the n-dimensional unit-cube:



()

<ロ> (四) (四) (王) (王) (王)

a) The inverse images y of the extremepoints of  $\hat{S}$  are extremepoints of the cuboid  $[y, \overline{y}]$  and have the following structure:

э

・ロト ・四ト ・ヨト ・ヨト

a) The inverse images y of the extreme points of  $\hat{S}$  are extreme points of the cuboid  $[y, \overline{y}]$  and have the following structure:

$$y = y_{\geq c}^{u} = \begin{cases} \overline{y}_{i} & \text{if } x_{i} \geq c \\ \underline{y}_{i} & \text{else} \end{cases}$$

э

・ロト ・四ト ・ヨト ・ヨト

(1)

a) The inverse images y of the extremepoints of  $\hat{S}$  are extremepoints of the cuboid  $[y, \overline{y}]$  and have the following structure:

$$y = y_{\geq c}^{u} = \begin{cases} \overline{y}_{i} & \text{if } x_{i} \geq c \\ \underline{y}_{i} & \text{else} \end{cases}$$
(1)

or

$$y = y_{\geq c}^{l} = \begin{cases} \underline{y}_{i} & \text{if } x_{i} \geq c \\ \overline{y}_{i} & \text{else }, \end{cases}$$

for some  $c \in \mathbb{R}$ .

(2)

a) The inverse images y of the extremepoints of  $\hat{S}$  are extremepoints of the cuboid  $[y, \overline{y}]$  and have the following structure:

$$y = y_{\geq c}^{u} = \begin{cases} \overline{y}_{i} & \text{if } x_{i} \geq c \\ \underline{y}_{i} & \text{else} \end{cases}$$

・ロト ・四ト ・ヨト ・ヨト

or

$$y = y_{\geq c}^{l} = \begin{cases} \underline{y}_{i} & \text{if } x_{i} \geq c \\ \overline{y}_{i} & \text{else }, \end{cases}$$

for some  $c \in \mathbb{R}$ . Here we call these y pseudodata.

3

(1)

(2)

a) The inverse images y of the extreme points of  $\hat{S}$  are extreme points of the cuboid  $[y, \overline{y}]$  and have the following structure:

$$y = y_{\geq c}^{u} = \begin{cases} \overline{y}_{i} & \text{if } x_{i} \geq c \\ \underline{y}_{i} & \text{else} \end{cases}$$
(1)

・ロト ・四ト ・ヨト ・ヨト

or

$$y = y_{\geq c}^{l} = \begin{cases} \underline{y}_{i} & \text{if } x_{i} \geq c \\ \overline{y}_{i} & \text{else }, \end{cases}$$

for some  $c \in \mathbb{R}$ . Here we call these y pseudodata. It suffices to take only  $c = x_i, i = 1, ..., n$ . (2)

b) all pseudodata are mapped to the boundary of  $\hat{S}$ .

2

ヘロト ヘアト ヘビト ヘビト

- b) all pseudodata are mapped to the boundary of  $\hat{S}$ .
- c) if there are no ties in x, then all pseudodata are actually mapped to extremepoints of  $\hat{S}$ .

・ロト ・個ト ・ヨト ・ヨトー

- b) all pseudodata are mapped to the boundary of  $\hat{S}$ .
- c) if there are no ties in x, then all pseudodata are actually mapped to extremepoints of  $\hat{S}$ .
- $\Rightarrow$  it suffices to look at all pseudodata instead of the whole cuboid to observe  $\hat{S}$ :

イロト イポト イヨト イヨト

- b) all pseudodata are mapped to the boundary of  $\hat{S}$ .
- c) if there are no ties in x, then all pseudodata are actually mapped to extremepoints of  $\hat{S}$ .
- $\Rightarrow$  it suffices to look at all pseudodata instead of the whole cuboid to observe  $\hat{S}$ :

$$\hat{S}={\sf co}\;\{A\cdot y|y\;$$
 is a pseudodata  $\}$ 

・ロト ・ 日 ・ ・ ヨ ・ ・ ヨ ・

\$\hinspace{S}\$ as the linear image of the minkowski mean of line segments, which could be also seen as the linear image of the minkowski mean of the set-valued data point (\$p\_1, \ldots, p\_n\$):

・ロト ・四ト ・ヨト ・ヨト

\$\hinspace{S}\$ as the linear image of the minkowski mean of line segments, which could be also seen as the linear image of the minkowski mean of the set-valued data point (\$p\_1, \ldots, p\_n\$):

$$\hat{S} = P \cdot \left(\frac{1}{n} \bigoplus_{i=1}^{n} p_i\right)$$

・ロト ・四ト ・ヨト ・ヨト

\$\hinspace{S}\$ as the linear image of the minkowski mean of line segments, which could be also seen as the linear image of the minkowski mean of the set-valued data point (\$p\_1, \ldots, p\_n\$):

$$\hat{S} = P \cdot \left( \frac{1}{n} \bigoplus_{i=1}^{n} p_i \right)$$

Since 
$$\hat{S} = \left\{ P \cdot \left( \begin{array}{c} \frac{1}{n} \sum_{i=1}^{n} y_i \\ \prod_{i=1}^{n} x_i \cdot y_i \end{array} \right) \middle| y \in [\underline{y}, \overline{y}] \right\}$$

\$\hinspace{S}\$ as the linear image of the minkowski mean of line segments, which could be also seen as the linear image of the minkowski mean of the set-valued data point (p<sub>1</sub>,..., p<sub>n</sub>):

$$\hat{S} = P \cdot \left(\frac{1}{n} \bigoplus_{i=1}^{n} p_i\right)$$

Since 
$$\hat{S} = \left\{ P \cdot \begin{pmatrix} \frac{1}{n} \sum_{i=1}^{n} y_i \\ \frac{1}{n} \sum_{i=1}^{n} x_i \cdot y_i \end{pmatrix} \middle| y \in [\underline{y}, \overline{y}] \right\}$$

we could understand  $\hat{S}$  as a point-estimator, which estimates the linear image of the (set-valued) so called Aumann Expectation

イロト 不得 とうせい イヨト

\$\hfrac{S}{s}\$ as the linear image of the minkowski mean of line segments, which could be also seen as the linear image of the minkowski mean of the set-valued data point (p<sub>1</sub>,..., p<sub>n</sub>):

$$\hat{S} = P \cdot \left(\frac{1}{n} \bigoplus_{i=1}^{n} p_i\right)$$

Since 
$$\hat{S} = \left\{ P \cdot \begin{pmatrix} \frac{1}{n} \sum_{i=1}^{n} y_i \\ \frac{1}{n} \sum_{i=1}^{n} x_i \cdot y_i \end{pmatrix} \middle| y \in [\underline{y}, \overline{y}] \right\}$$

we could understand  $\hat{S}$  as a point-estimator, which estimates the linear image of the (set-valued) so called Aumann Expectation

$$\left\{ \begin{pmatrix} \mathbb{E}(Y) \\ \mathbb{E}(X \cdot Y) \end{pmatrix} \middle| Y \in [\underline{Y}, \overline{Y}] \right\} \text{ under } P$$

イロト 不得 とうせい イヨト

(1)  $\hat{S}$  as the linear image of the minkowski mean of line segments, which could be also seen as the linear image of the minkowski mean of the set-valued data point  $(p_1, \ldots, p_n)$ :

$$\hat{S} = P \cdot \left(\frac{1}{n} \bigoplus_{i=1}^{n} p_i\right)$$

Since 
$$\hat{S} = \left\{ P \cdot \begin{pmatrix} \frac{1}{n} \sum_{i=1}^{n} y_i \\ \frac{1}{n} \sum_{i=1}^{n} x_i \cdot y_i \end{pmatrix} \middle| y \in [\underline{y}, \overline{y}] \right\}$$

we could understand  $\hat{S}$  as a point-estimator, which estimates the linear image of the (set-valued) so called Aumann Expectation

$$\left\{ \begin{pmatrix} \mathbb{E}(Y) \\ \mathbb{E}(X \cdot Y) \end{pmatrix} \middle| Y \in [\underline{Y}, \overline{Y}] \right\} \text{ under } P \text{ (often called the sharp identification region).}$$

So  $\hat{S}$  could at first hand be seen as a (set-valued) pointestimator for a (set-valued) parameter (the Aumann Expectation under P). Here we can use random set theory to analyze the estimator.

(2)  $\hat{S}$  as the collection of all precise pointestimators obtained by all possible data-completions  $y \in [\underline{y}, \overline{y}]$ .

2

2

・ロン ・四 と ・ ヨン ・ ヨン

(1) analyze or estimate the distribution of the pointestimator  $\hat{S}$  to construct a confidenceregion.

・ロト ・四ト ・ヨト ・ヨト

(1) analyze or estimate the distribution of the pointestimator  $\hat{S}$  to construct a confidenceregion. Since  $\hat{S}$  is set-valued, we need a propper metric for the space of sets in  $\mathbb{R}^d$ :

< 日 > < 同 > < 三 > < 三 > < 三 > <

(1) analyze or estimate the distribution of the pointestimator  $\hat{S}$  to construct a confidenceregion. Since  $\hat{S}$  is set-valued, we need a propper metric for the space of sets in  $\mathbb{R}^d$ :

one suggestion often quoted as natural:

(1) analyze or estimate the distribution of the pointestimator  $\hat{S}$  to construct a confidenceregion. Since  $\hat{S}$  is set-valued, we need a propper metric for the space of sets in  $\mathbb{R}^d$ :

one suggestion often quoted as natural: the Hausdorff Distance:

(1) analyze or estimate the distribution of the pointestimator  $\hat{S}$  to construct a confidenceregion. Since  $\hat{S}$  is set-valued, we need a propper metric for the space of sets in  $\mathbb{R}^d$ :

one suggestion often quoted as natural: the Hausdorff Distance:

 $H(A,B) := max\{dH(A,B), dH(B,A)\}$ 

・ロン ・四 ・ ・ ヨン ・ ヨン

(1) analyze or estimate the distribution of the pointestimator  $\hat{S}$  to construct a confidenceregion. Since  $\hat{S}$  is set-valued, we need a propper metric for the space of sets in  $\mathbb{R}^d$ :

one suggestion often quoted as natural: the Hausdorff Distance:

 $H(A,B) := max\{dH(A,B), dH(B,A)\}$ 

with the directed Hausdorff Distance

(1) analyze or estimate the distribution of the pointestimator  $\hat{S}$  to construct a confidenceregion. Since  $\hat{S}$  is set-valued, we need a propper metric for the space of sets in  $\mathbb{R}^d$ :

one suggestion often quoted as natural: the Hausdorff Distance:

 $H(A,B) := max\{dH(A,B), dH(B,A)\}$ 

with the directed Hausdorff Distance

 $dH(A,B) := \sup_{a \in A} \inf_{b \in B} d(a,b)$ 

(1) analyze or estimate the distribution of the pointestimator  $\hat{S}$  to construct a confidenceregion. Since  $\hat{S}$  is set-valued, we need a propper metric for the space of sets in  $\mathbb{R}^d$ :

one suggestion often quoted as natural: the Hausdorff Distance:

 $H(A,B) := max\{dH(A,B), dH(B,A)\}$ 

with the directed Hausdorff Distance

 $dH(A,B) := \sup_{a \in A} \inf_{b \in B} d(a,b)$ 

and a metric d in  $\mathbb{R}^d$  (e.g. the euclidean metric).

This approach is developed in Beresteanu, Molinari 2008:

《曰》 《圖》 《臣》 《臣》
There the authors estimate  $\hat{S}$  and draw bootstrap-samples from the data to estimate further  $\hat{S}^*$  and look on the distribution of  $dH(\hat{S}^*, \hat{S})$ .

・ロト ・ 日 ・ ・ ヨ ・ ・ 日 ・ ・

$$HCR = \bigcup_{\substack{\boldsymbol{s} \in \mathbb{R}^{\boldsymbol{d}} \\ dH(S,\hat{S}) < c_{\alpha}}} S.$$

・ロト ・日下・ ・日下・

$$HCR = \bigcup_{\substack{\boldsymbol{s} \subset \mathbb{R}^{d} \\ dH(S, \hat{S}) \leq c_{\alpha}}} S.$$

This confidence region asymptotically covers the whole sharp identification region with probability at least  $1-\alpha$ 

・ロト ・ 日 ・ ・ ヨ ・ ・ ヨ ・

$$HCR = \bigcup_{\substack{\boldsymbol{s} \in \mathbb{R}^{d} \\ dH(S, \hat{S}) \leq c_{\alpha}}} S.$$

This confidence region asymptotically covers <u>the whole</u> sharp identification region with probability at least  $1 - \alpha$  (under some regularity assumptions).

$$HCR = \bigcup_{\substack{\boldsymbol{s} \subset \mathbb{R}^{\boldsymbol{d}} \\ dH(S, \hat{S}) \leq c_{\alpha}}} S.$$

This confidence region asymptotically covers <u>the whole</u> sharp identification region with probability at least  $1 - \alpha$  (under some regularity assumptions).

If one is in the situation, that there is a precise parameter  $\beta$  behind the scenes, it would be sufficient, that a confidence region covers not necessarily the whole sharp identification region but only the true parameter  $\beta$  with at least probability  $1 - \alpha$ , which is a weaker demand. So in this situation HCR is a (conservative) confidence region for the true parameter  $\beta$ .

(2) collect the classical confidence-elipsoides for the classical least-squares-estimator and all possible data y ∈ [y, y]:

э

 (2) collect the classical confidence-elipsoides for the classical least-squares-estimator and all possible data y ∈ [y, y]:

$$SCR := \bigcup_{y \in [\underline{y}, \overline{y}]} CE(y)$$

э

 (2) collect the classical confidence-elipsoides for the classical least-squares-estimator and all possible data y ∈ [y, y]:

$$SCR := \bigcup_{y \in [\underline{y}, \overline{y}]} CE(y)$$

with the classical confidence-ellipsoides

 (2) collect the classical confidence-elipsoides for the classical least-squares-estimator and all possible data y ∈ [y, y]:

$$SCR := \bigcup_{y \in [\underline{y}, \overline{y}]} CE(y)$$

with the classical confidence-ellipsoides

 $CE(y) := \left\{\beta | \left(\beta - \hat{\beta}(y)\right)'(X'X)(\beta - \hat{\beta}(y)) \le (p+1) \cdot \hat{\sigma}^2(y) \cdot F_{1-\alpha}(p+1, n-p+1)\right\}.$ 

But how do we compute this confidence region?

2

イロト イポト イヨト イヨト

But how do we compute this confidence region?

### Lemma

Let a partially identified linear model  $y = \beta_0 + \beta_1 \cdot x + \varepsilon$  be given.

э

But how do we compute this confidence region?

#### Lemma

Let a partially identified linear model  $y = \beta_0 + \beta_1 \cdot x + \varepsilon$  be given. Under some not too strong conditions the simple confidenceregion SCR is a subset of the ellipsoid-type-confidenceregion

$$ECR := \operatorname{co} \left( \bigcup_{c \in \{x_1, \dots, x_n\}} CE(y_{\geq c}^u) \cup CE(y_{\geq c}^l) \right)$$

with arbitrary high probability p < 1, if n = n(p) is large enough.

One ,,real-world-example":

2

・ロン ・四 と ・ ヨン ・ ヨン

One ,,real-world-example": Allbus data:

2

One "real-world-example": Allbus data:

• sample from East Germany (n = 1077)

2

・ロト ・ 日 ・ ・ ヨ ・ ・ 日 ・ ・

One "real-world-example": Allbus data:

- sample from East Germany (n = 1077)
- age (x, precise) and logarithm of income (y, interval-valued)







30 / 48

(中) (종) (종) (종) (종)

- Beresteanu, A., Molinari, F. (2008) Asymptotic Properties for a Class of Partially Identified Models, Econometrica, vol. 76, issue 4, pages 763-814.
- Schön, S., Kutterer, H. (2004) Using Zonotopes for Overestimation-Free Interval Least-Squares - Some Geodetic Applications. Reliable Computing, vol. 11, pages 137-155.
- Cerny, M., Rada M. (2011). On the Possibilistic Approach to Linear Regression with Rounded or Interval-Censored Data. Measurement Science Review, vol. 11 No. 2.

()

2

for 4 coarsening-processes:

2

イロト イロト イヨト イヨト

for 4 coarsening-processes:

• coarsening 1: 
$$y = 10 \cdot x + 10 + \varepsilon$$
,  $\varepsilon \sim N(0, 1)$   
 $y = y - \exp(\varepsilon_2)$ ,  $\overline{y} = y + \exp(\varepsilon_3)$ ,  $\varepsilon, \varepsilon_2, \varepsilon_3 : i.i.d., \sim N(0, 1)$ ,

2

・ロト ・日本・ ・ 日本・

for 4 coarsening-processes:

()

- coarsening 1:  $y = 10 \cdot x + 10 + \varepsilon$ ,  $\varepsilon \sim N(0, 1)$  $\underline{y} = y - \exp(\varepsilon_2)$ ,  $\overline{y} = y + \exp(\varepsilon_3)$ ,  $\varepsilon, \varepsilon_2, \varepsilon_3 : i.i.d., \sim N(0, 1)$ ,
- coarsening 2:  $\underline{y} = min\{y, y_2\}, \quad \overline{y} = max\{y, y_2\}, \quad y_2 = 13 \cdot x + 9 + \varepsilon_2$

(日) (周) (王) (王) (王)

for 4 coarsening-processes:

- coarsening 1:  $y = 10 \cdot x + 10 + \varepsilon$ ,  $\varepsilon \sim N(0, 1)$   $\underline{y} = y - \exp(\varepsilon_2)$ ,  $\overline{y} = y + \exp(\varepsilon_3)$ ,  $\varepsilon, \varepsilon_2, \varepsilon_3 : i.i.d., \sim N(0, 1)$ , • coarsening 2:  $\underline{y} = min\{y, y_2\}$ ,  $\overline{y} = max\{y, y_2\}$ ,  $y_2 = 13 \cdot x + 9 + \varepsilon_2$
- coarsening 3:  $\underline{y} = y \varepsilon_2^2 \cdot 10^{-5}$ ,  $\overline{y} = y + \varepsilon_3^2 \cdot 10^{-5} \cdot p$ ,  $p \sim B(n, 0.05)$

for 4 coarsening-processes:

• coarsening 1: 
$$y = 10 \cdot x + 10 + \varepsilon$$
,  $\varepsilon \sim N(0, 1)$   
 $\underline{y} = y - \exp(\varepsilon_2)$ ,  $\overline{y} = y + \exp(\varepsilon_3)$ ,  $\varepsilon$ ,  $\varepsilon_2$ ,  $\varepsilon_3 : i.i.d.$ ,  $\sim N(0, 1)$ ,  
• coarsening 2:  $\underline{y} = min\{y, y_2\}$ ,  $\overline{y} = max\{y, y_2\}$ ,  $y_2 = 13 \cdot x + 9 + \varepsilon_2$   
• coarsening 3:  $\underline{y} = y - \varepsilon_2^2 \cdot 10^{-5}$ ,  $\overline{y} = y + \varepsilon_3^2 \cdot 10^{-5} \cdot p$ ,  $p \sim B(n, 0.05)$   
• coarsening 4:  $\underline{y} = p \cdot y + (1 - p) \cdot min\{-200, y\}$   
 $\overline{y} = y + \varepsilon^2 \cdot q$   
 $p \sim B(n, u_1)$ ,  $u_1 \sim u[0, 1]$   
 $q \sim B(n, u_2^2)$ ,  $u_2 \sim u[0, 1]$ 

2

## Covering Probabilities:

()

イロト イロト イヨト イヨト 三日

# Covering Probabilities:

coarsening	Ν	SIR	HCR	ECR
1	10	0.96	1	1
1	100	1	1	1
1	1000	1	1	1
2	10	0.43	1	0.99
2	100	0.59	0.99	0.99
2	1000	0.80	1	1
3	10	0	0.93	1
3	100	0	0.92	0.95
3	1000	0	0.96	0.95
4	10	0.22	1	1
4	100	0.54	1	1
4	1000	0.82	1	1

イロト イロト イヨト イヨト 三日

()

Areas:

()

◆□ > ◆□ > ◆臣 > ◆臣 > ○ 臣 ○ ○ ○ ○

#### Areas:

coarsening	Ν	SIR	HCR	ECR
1	10	7.18	102.33	55.40
1	100	6.22	14.31	13.07
1	1000	6.14	8.62	8.08
2	10	5.33	25.81	22.90
2	100	5.60	8.79	8.67
2	1000	5.62	6.57	6.51
3	10	$7 \cdot 10^{-11}$	3.97	3.37
3	100	$6.29 \cdot 10^{-11}$	0.19	0.19
3	1000	$6.39 \cdot 10^{-11}$	0.02	0.02
4	10	9.90	15848.89	10485.69
4	100	1.22	142.84	87.30
4	1000	0.31	1.48	1.25

◆□ > ◆□ > ◆臣 > ◆臣 > ○ 臣 ○ ○ ○ ○

# An Idea of robustification

()

linear models and partial identification

2

1) a bad idea:

2

・ロン ・四 と ・ ヨン ・ ヨン

1) a bad idea:

apply a robust method to all pseudodata.

2



()



◆□▶ ◆圖▶ ◆理≯ ◆理≯ 三連。

()


◆□> ◆圖> ◆国> ◆国> 三国

()



()

◆□▶ ◆圖▶ ◆理≯ ◆理≯ 三連。



(中) (종) (종) (종) (종)

2

・ロト ・四ト ・ヨト ・ヨト

find for all pseudodata an appropriate (pseudo-)weightvector p.



э

・ロト ・個ト ・ヨト ・ヨトー

find for all pseudodata an appropriate (pseudo-)weightvector p.

• Calculate a global weight-vector g, that is acceptable in relation to all pseudoweightvectors

・ロト ・四ト ・ヨト ・ヨト

find for all pseudodata an appropriate (pseudo-)weightvector p.

• Calculate a global weight-vector g, that is acceptable in relation to all pseudoweightvectors in the sense, that g lies between 1 and p for every pseudoweightvector p.

find for all pseudodata an appropriate (pseudo-)weightvector p.

- Calculate a global weight-vector g, that is acceptable in relation to all pseudoweightvectors in the sense, that g lies between 1 and p for every pseudoweightvector p.
- Now use the weighted least-sugres-estimator with this weights.

find for all pseudodata an appropriate (pseudo-)weightvector p.

- Calculate a global weight-vector g, that is acceptable in relation to all pseudoweightvectors in the sense, that g lies between 1 and p for every pseudoweightvector p.
- Now use the weighted least-sugres-estimator with this weights. All properties of the unweighted zonotope-estimator are kept.

find for all pseudodata an appropriate (pseudo-)weightvector p.

- Calculate a global weight-vector g, that is acceptable in relation to all pseudoweightvectors in the sense, that g lies between 1 and p for every pseudoweightvector p.
- Now use the weighted least-sugres-estimator with this weights. All properties of the unweighted zonotope-estimator are kept.
- For confidenceregions use the Hausdorff-based approach of Beresteanu and Molinari, but maybe with another *d* in the definition of the Hausdorff-distance.



◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 三臣。









46 / 48

## Covering Probabilities:

()

イロト イロト イヨト イヨト 三日

## Covering Probabilities:

coarsening	Ν	SIR	HCR	ECR	GRHCR
1	10	0.96	1	1	1
1	100	1	1	1	1
1	1000	1	1	1	1
2	10	0.43	1	0.99	1
2	100	0.59	0.99	0.99	1
2	1000	0.80	1	1	1
3	10	0	0.93	1	1
3	100	0	0.92	0.95	0.95
3	1000	0	0.96	0.95	0.96
4	10	0.22	1	1	
4	100	0.54	1	1	1
4	1000	0.82	1	1	1

イロト イロト イヨト イヨト 三日

Areas:

()

◆□ > ◆□ > ◆臣 > ◆臣 > ○ 臣 ○ ○ ○ ○

## Areas:

coarsening	Ν	SIR	HCR	ECR	GRHCR
1	10	7.18	119.55	32.522	120.38
1	100	6.22	14.31	13.07	13.59
1	1000	6.14	8.62	8.08	7.90
2	10	5.33	25.81	22.90	24.57
2	100	5.60	8.79	8.67	8.56
2	1000	5.62	6.57	6.51	6.24
3	10	$7 \cdot 10^{-11}$	3.97	3.37	3.99
3	100	$6.29 \cdot 10^{-11}$	0.19	0.19	0.2
3	1000	$6.39 \cdot 10^{-11}$	0.02	0.02	0.02
4	10	9.90	15848.89	10485.69	15994.15
4	100	1.22	142.84	87.30	110.02
4	1000	0.31	1.48	1.25	

◆□ > ◆□ > ◆臣 > ◆臣 > ○ 臣 ○ ○ ○ ○

- Beresteanu, A., Molinari, F. (2008) Asymptotic Properties for a Class of Partially Identified Models, Econometrica, vol. 76, issue 4, pages 763-814.
- Schön, S., Kutterer, H. (2004) Using Zonotopes for Overestimation-Free Interval Least-Squares - Some Geodetic Applications. Reliable Computing, vol. 11, pages 137-155.
- Cerny, M., Rada M. (2011). On the Possibilistic Approach to Linear Regression with Rounded or Interval-Censored Data. Measurement Science Review, vol. 11 No. 2.